

Nalini Joshi

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Lp

Newton said "I seem to have been only like a boy playing on the seashore and diverting myself in now and then finding a smoother pebble or prettier shell than ordinary, whilst the great ocean of truth lay a undiscovered before me."



The aim of these lectures is to show some of the beautiful pebbles and shells I know, which are discrete Painlevé equations.

§1 Introduction

In 1939, Shohat (Duke Math. J. 5 (2) (1939) 401-417) extended the study of orthogonal polynomials $\{\Phi_n(x)\}_{n=0}^{\infty}$ to the class with weight $p(x)$

$$\int_a^b p(x) \Phi_m(x) \Phi_n(x) dx = 0, \quad m \neq n, \quad m, n \in \mathbb{N}$$

s.t.

$$p(x) = \frac{1}{A(x)} \exp\left(\int_a^b \frac{B(x)}{A(x)} dx\right), \quad \text{with } A \neq 0 \text{ in } (a, b)$$

In the case $a = -\infty, b = \infty, p(x) = \exp(-x^4/4)$, he obtained

$$\lambda_{n+2} (\lambda_{n+1} + \lambda_{n+2} + \lambda_{n+3}) = n+1 \quad (1.1)$$

where λ_n is related to the 3-term recurrence relation

$$\Phi_n(x) - (x - c_n) \Phi_{n-1}(x) + \lambda_n \Phi_{n-2}(x) = 0, \quad n \geq 2$$

$$\Phi_0 = 1, \Phi_1 = x - c_1$$

Eqn (1.1) is a special case of what is now called the first discrete Painlevé equation: $(dP_1) :$

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$$w_n (w_{n+1} + w_n + w_{n-1}) = \alpha n + \beta + \delta(-1)^n + \gamma w_n \quad (1-2)$$

where $\alpha, \beta, \gamma, \delta$ are consts.

The name comes from its continuum limit. Take $\delta=0$ and write

$$t = \varepsilon n, \quad w_n = \mu + \varepsilon^2 u(t), \quad u(t) \text{ assumed analytic}$$

$$\alpha = -\varepsilon^a v, \quad \beta = -\frac{\gamma^2}{12}$$

then

$$w_{n\pm 1} = \mu + \varepsilon^2 u(t \pm \varepsilon)$$

$$= \mu + \varepsilon^2 \left\{ u(t) \pm \varepsilon u_t(t) + \frac{\varepsilon^2}{2} u_{tt}(t) + O(\varepsilon^3) \right\}$$

So we get from (1-2):

$$(\mu + \varepsilon^2 u) (3\mu + 3\varepsilon^2 u + \varepsilon^4 u_{tt} + O(\varepsilon^6))$$

$$= -\varepsilon^{a-1} v t - \frac{\gamma^2}{12} + \gamma \mu + \gamma \varepsilon^2 u$$

Take

$$3\mu^2 = \gamma \mu - \frac{\gamma^2}{12}$$

$$6\mu = \gamma$$

$$3\mu^2 = \gamma/6 - \gamma^2/12 = \gamma^2/12$$

$$\Rightarrow \mu = \gamma/6 \quad \text{IP}$$

and

$$a-1 = 4$$

$\Rightarrow$

$$\mu u_{tt} + 3u^2 = -vt + O(\varepsilon^2)$$

Taking $\mu = -\frac{1}{2}$, $v = -\mu$, we get as $\varepsilon \rightarrow 0$

$$u_{tt} = 6u^2 + t$$

the first Painlevé eqn P_I , one of six classical Painlevé eqns denoted $P_I - P_{VI}$.

Equation (1-2) is not the only discrete version of P_I .

For example: using the notation $w = w_n$, $\bar{w} = w_{n+1}$, $\underline{w} = w_{n-1}$.

$$\frac{\bar{z}}{\bar{w} + w} + \frac{z}{w + \underline{w}} + 2w^2 + t = 0$$

the "alternative dP_I "

where z is linear in n & t .

$$w_{n+1}, w_{n-1} = \frac{w_n - t_0 q^n}{w_n^2}, \quad q \neq 0, 1 \quad (1-5)$$

q -discrete P_I or qP_I

where t_0, q are consts

are both integrable discrete versions of P_I .

The case $\delta \neq 0$ of Eqn (1-2) has to be converted to a syst. before attempting a continuum limit, i.e. define

$$w_{2k} = u_k$$

$$w_{2k+1} = v_k$$

$$\text{Case } n=2k: \quad u_k (v_k + u_k + v_{k-1}) = \frac{2\alpha k + \beta + \delta}{u_k} + \gamma \quad (1-3)$$

$$\text{Case } n=2k+1: \quad v_k (u_{k+1} + v_k + u_k) = \frac{(2\alpha k + \alpha + \beta - \delta)}{v_k} + \gamma \quad (1-4)$$

The system (1.3)-(1.4) is often called the "asymmetric" dP_I .
(In Japan, it is called dP_2 .)

Exercise: show that (1.3)-(1.4) has a continuum limit to

$$y_{tt} = 2y^3 + ty + a, \quad a \text{ is const}$$

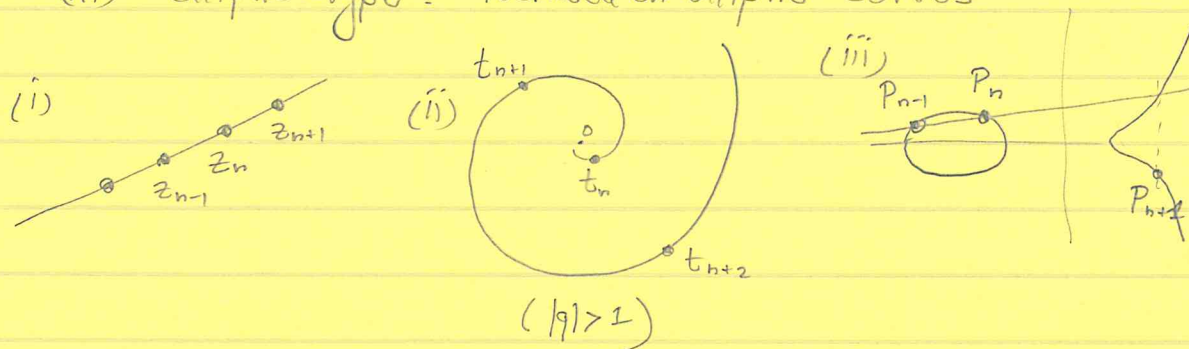
which is P_{II} .

In general, $\exists$ three-types of discrete Painlevé equations (DPEs)

(i) additive-type = iterated on a straight line $z_n = \alpha n + \beta$
like (1.3)-(1.4)

(ii) multiplicative - or q-type = iterated on a spiral $t_n = t_0 q^n$
like (1.5)

(iii) elliptic-type = iterated on elliptic curves



Type (i) DPEs arise as recurrence relations from transformations of ODEs. Consider $P_{\text{IV}}(w, t; a, b)$:

$$W'' = \frac{W'^2}{2W} + \frac{3W^3}{2} + 4tW^2 + 2(t^2 - a)W - \frac{b^2}{2W} \quad (1.6)$$

which has Bäcklund transformations: mapping

$$P_{\text{IV}}(w_n, t; a_n, b_n) \mapsto P_{\text{IV}}(w_{n+1}, t; a_{n+1}, b_{n+1})$$

with

$$a_n = -\frac{n}{2} - \frac{c_0}{2} + \frac{3c_1}{2}(-1)^n$$

$$b_n = n + c_0 + c_1(-1)^n \quad c_0, c_1 \text{ const.}$$

$$2w_n w_{n+1} = -w_n' - w_n^2 - 2tw_n + b_n \quad (1.7a)$$

$$2w_n w_{n-1} = w_n' - w_n^2 - 2tw_n + b_n \quad (1.7b)$$

Adding, we get

$$2w_n (w_{n+1} + w_{n-1} + w_n) = -4tw_n + 2b_n$$

which is (1.2) with $\gamma = -2t$, $\alpha = 1$, $\beta = c_0$, $\delta = c_1$.

Such transformations are simpler to understand in terms of reflection.

To see this, consider the symmetric form of P_{IV} :

$$\dot{f}_0 = f_0(f_1 - f_2) + \alpha_0, \quad \dot{f}_j = f_j(s)$$

$$\dot{f}_1 = f_1(f_2 - f_0) + \alpha_1,$$

$$\dot{f}_2 = f_2(f_0 - f_1) + \alpha_2,$$

where $f_0 + f_1 + f_2 = s$, $\alpha_0 + \alpha_1 + \alpha_2 = 1$.

Exercise: Eliminate f_1, f_2 and show that $f_0(s) = \mu w(t)$

with $t = \lambda s$ satisfies P_{IV} (eqn (1.6)) for some $\lambda, \mu, \alpha, \delta$.

The BTs can be written in terms of the operations:

$$s_i(\alpha_i) = -\alpha_i \quad s_i(\alpha_j) = \alpha_j + \alpha_i, \quad j = i \pm 1, \quad \Pi(\alpha_j) = \alpha_{j+1}$$

$$s_i(f_i) = f_i \quad s_i(f_j) = f_j \pm \frac{\alpha_j}{f_i}, \quad j = i \pm 1, \quad \Pi(f_j) = f_{j+1}$$

$j \in \mathbb{N} \pmod{3}$.

See Noumi & Yamada (1989)

Okamoto (1986)

For example, the BT (1.7a) arises if we take

$$T = \Pi \circ s_2 \circ s_1$$

$$\begin{aligned} \text{Check } T(\alpha_0) &= \Pi \circ s_2(s_1(\alpha_0)) \\ &= \Pi \circ s_2(\alpha_1 + \alpha_0) \\ &= \Pi(s_2(1 - \alpha_2)) \\ &= \Pi(1 + \alpha_2) \\ &= 1 + \alpha_0. \end{aligned}$$

Exercise: See also Tutorial 1, Q 1. Show that $T(f_0)$ is related to the BTs (1.7).

The operations s_j, Π satisfy $s_j^2 = 1$, $(s_j s_{j+1})^3 = 1$, $\Pi^3 = 1$, $\Pi s_j = s_{j+1} \Pi$.

These properties make the span

$W = \langle s_0, s_1, s_2 \rangle$ an affine Weyl (Coxeter) group or system,

and

$\tilde{W} = \langle s_0, s_1, s_2, \pi \rangle$ an extended affine Weyl group

The root system associated with P_{IV} is $A_2^{(1)}$. (We explore this further in Lecture 2.)

Sakai (2001) showed $\exists$ 22 classes of DPEs described by root sys.

$\Leftrightarrow$ initial value spaces

Type of iteration	Type of Initial Value Space
Elliptic	$A_0^{(1)}$
Multiplicative	$A_0^{(1)*}, A_1^{(1)}, \dots, A_8^{(1)}, A_7^{(1)'}$
Elliptic	$A_0^{(1)**}, A_1^{(1)*}, A_2^{(1)*}, D_4^{(1)}, \dots, D_8^{(1)}, E_6^{(1)}, \dots, E_8^{(1)}$

Each equation also has a symmetry group. To be a DPE, time iteration has to be a translation on the root lattice.

In these lectures, I will show how to construct

- the initial value space
- the symmetry group

of a given DPE and, conversely, given a parametrization of the initial value space, how to construct the corresponding DPE. I will focus on examples.

DPEs are pretty shells - but a lot can be understood about their solutions by understanding Sakai's theory.